Smart responsive gels

Designing the building blocks of squishy bio-inspired devices

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Joseph Webber Mathematics Institute, University of Warwick

LEVERHULME TRUST



Why bother?



 Hydrogels: formed from cross-linked networks of hydrophilic polymer chains surrounded by adsorbed water molecules – often >90% water by volume



- Soft, squishy (low shear modulus), stretchable solids, porous in nature and can support significant interstitial flows. Easy and cheap to manufacture, but also found naturally.
 - Hydrogels are found in biological tissues: collagen/cellulose/starch
 - Models for biofilms?
 - Water transport in vascular plants?

- Highly biocompatible owing to water content
- Drug delivery
- Tissue engineering
- "Passive" gels are everywhere: nappy filling, concrete additives, contact lenses, water retention for agriculture, evaporative cooling, ...

Hyperelastic and entropic models

• Linear poroelasticity is no good – strains of O(10) are possible. Need to capture nonlinearity.

$$W = \frac{k_B T}{2\Omega_p} [\operatorname{tr} (\mathsf{F}_{ij}\mathsf{F}_{ji}) - 3 + 2\log\phi] + \frac{k_B T}{\Omega_f} \left[\frac{1 - \phi}{\phi} \log(1 - \phi) + \chi(\phi, T)(1 - \phi) \right]$$

Elastic part
(Gaussian-chain model)
- *F* is the deformation
gradient tensor
- Ω_p is the volume of a
single polymer chain

$$\frac{k_B T}{\Omega_f} \left[\frac{1 - \phi}{\phi} \log(1 - \phi) + \chi(\phi, T)(1 - \phi) \right]$$

Mixing part
(Flory-Huggins model)
- χ is interaction parameter (hard to fit!)
- Ω_f is the volume of a single solvent
(water) molecule

 Chemical potential + Thermodynamics + Darcy flow = model for gel dynamics (e.g. <u>Cai & Suo JMPS</u> 2011, <u>Butler & Montenegro-Johnson JFM 2022</u>)

Hyperelastic and entropic models

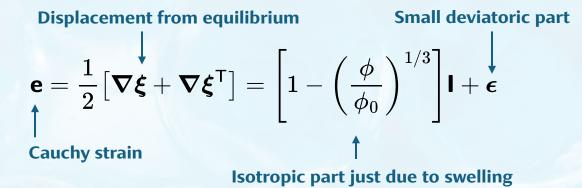
$$W = rac{k_BT}{2\Omega_p}[ext{tr}\left(\mathsf{F}_{ij}\mathsf{F}_{ji}
ight) - 3 + 2\log\phi] + rac{k_BT}{\Omega_f}iggl[rac{1-\phi}{\phi}\log{(1-\phi)} + \chi(\phi,\,T)(1-\phi)iggr]$$

- Gives good predictions such as the **swollen equilibrium polymer fraction** ϕ_o
- But... unsatisfactory for a number of reasons:
 - Messy system of lots of equations: needs numerical solution
 - What motivates our elastic or mixing models? Are they valid?
 - Steady states: easy. Transient behaviour: hard.
 - Fitted parameters don't easily correspond to macroscopically-measurable phenomena
- Some other approaches have been taken to fix this:
 - Large-strain poroelasticity (Bertrand et al., Phys Rev Appl 2016)
 - Linear poroelasticity for small swelling (Doi, J Phys Soc Jpn 2009)

Webber & Worster and Webber, Etzold & Worster JFM, 2023

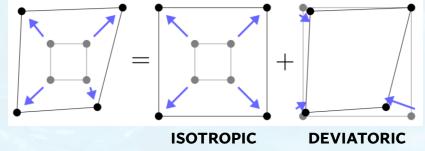


 Key idea: allow for nonlinearity in isotropic strains corresponding to swelling/deswelling but linearise around deviatoric strains that must be small. Measure all displacements relative to the fully-swollen equilibrium.



Shear modulus $\downarrow \\ \boldsymbol{\sigma} = -P \mathbf{I} + 2 \mu_s(\phi) \boldsymbol{\epsilon}$ \uparrow Cauchy stress

- Pressure is taken to have contributions from the water phase, hydrophilic effects, and bulk (isotropic) elasticity, so take $P = p + \Pi$
 - *p* is the **pervadic**, **pore**, or **Darcy** pressure
 - *Π* is the **generalised osmotic pressure**



Webber & Worster and Webber, Etzold & Worster JFM, 2023



- A gel, swollen to any degree, can be described using three material parameters: a shear modulus μ_s(φ), an osmotic pressure Π(φ) and a permeability k(φ)
- This treats the gel as linear elastic with (potentially) nonlinear properties, each of which is macroscopically meaningful:
 - The shear modulus governs the initial incompressible response to forcing
 - The osmotic pressure governs the steady state reached where water is expelled or drawn in
 - The permeability sets the timescale over which an adjustment occurs

Webber & Worster and Webber, Etzold & Worster JFM, 2023



$$\mathbf{e} = rac{1}{2}ig[oldsymbol{
abla} oldsymbol{\xi} + oldsymbol{
abla} oldsymbol{\xi}^{\mathsf{T}} ig] = igg[1 - igg(rac{\phi}{\phi_0} igg)^{1/3} igg] oldsymbol{\mathsf{I}} + oldsymbol{\epsilon}$$

$$oldsymbol{\sigma} = -\left[p + \Pi(\phi)
ight] {f I} + 2 \mu_s(\phi) oldsymbol{\epsilon}$$

$$oldsymbol{\iota} = -rac{k(\phi)}{\mu_l}oldsymbol{
abla} p$$

Combine with conservation of water, conservation of polymer, and force-free momentum balance

Phase-averaged flux of water and polymer

$$egin{aligned} rac{\partial \phi}{\partial t} + oldsymbol{q} \cdot oldsymbol{
abla} \phi &= oldsymbol{
abla} \cdot \left\{ rac{k(\phi)}{\mu_l} \left[\phi rac{\partial \Pi}{\partial \phi} + rac{4\mu_s(\phi)}{3} \left(rac{\phi}{\phi_0}
ight)^{1/3}
ight] oldsymbol{
abla} \phi
ight\} \end{aligned}$$

Slow nonlinear diffusion of water

Note: we have not prescribed constitutive laws, and can in fact deduce forms of the three parameters given, say, Flory-Huggins theory and Gaussian-chain elasticity

Webber & Worster and Webber, Etzold & Worster JFM, 2023



$$\mathbf{e} = rac{1}{2}ig[oldsymbol{
abla} oldsymbol{\xi} + oldsymbol{
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$$oldsymbol{\sigma} = -\left[p + \Pi(\phi)
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Phase-averaged flux of water and polymer

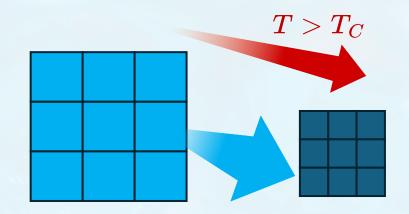
$$rac{\partial \phi}{\partial t} + oldsymbol{q} \cdot
abla \phi =
abla \cdot \left\{ rac{k(\phi)}{\mu_l} \left[\phi rac{\partial \Pi}{\partial \phi} + rac{4\mu_s(\phi)}{3} \left(rac{\phi}{\phi_0}
ight)^{1/3}
ight]
abla \phi
ight\}$$

Slow nonlinear diffusion of water

In general, need another piece of the puzzle (*Webber, Etzold & Worster, JFM 2023b*) to find displacement field $\nabla^4 \boldsymbol{\xi} = -3 \boldsymbol{\nabla} \nabla^2 (\phi/\phi_0)^{1/3}$

Responsive gels

- Gels can be engineered to respond to a number of external stimuli: heat, light, pH, chemical concentration...
- Thermo-responsive gels have a **lower critical solution temperature (LCST)** above which the polymer rapidly loses its affinity for water, leading to shrinkage. This process is reversible.
- Usually modelled by having a temperature-dependent Flory chi parameter, measuring the strength of intermolecular interactions between polymer and water
 - Constrains us to messy nonlinear approaches
 - Microscopic modelling is hard
 - Many different parameters to fit (<u>Butler & Montenegro-</u> <u>Johnson, JFM 2022</u>)



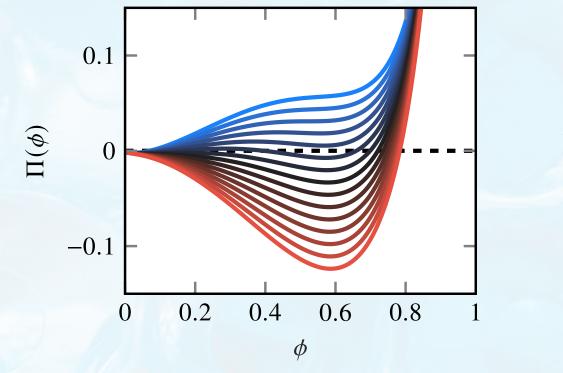
(Thermo-/chemo-/photo-)responsive LENS Osmotic "completely dry gel" $T < T_C$ pressure $\Pi(\phi)$ **Positive osmotic pressure** = propensity to swell, water drawn in ϕ_{00} **Negative osmotic pressure** = propensity to deswell, water driven out

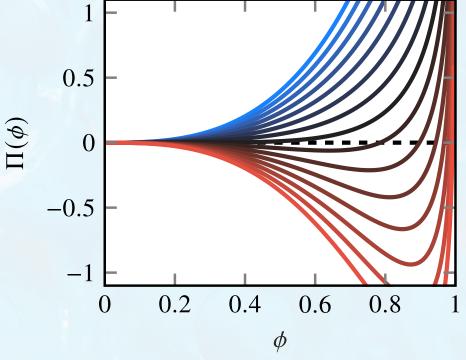
(Thermo-/chemo-/photo-)responsive LENS Osmotic "completely dry gel" $T < T_C$ pressure Above the LCST, there is a new, higher, equilibrium polymer fraction where $\Pi = 0$ $\phi_{0\infty}$ ϕ_{00} \mathcal{O}

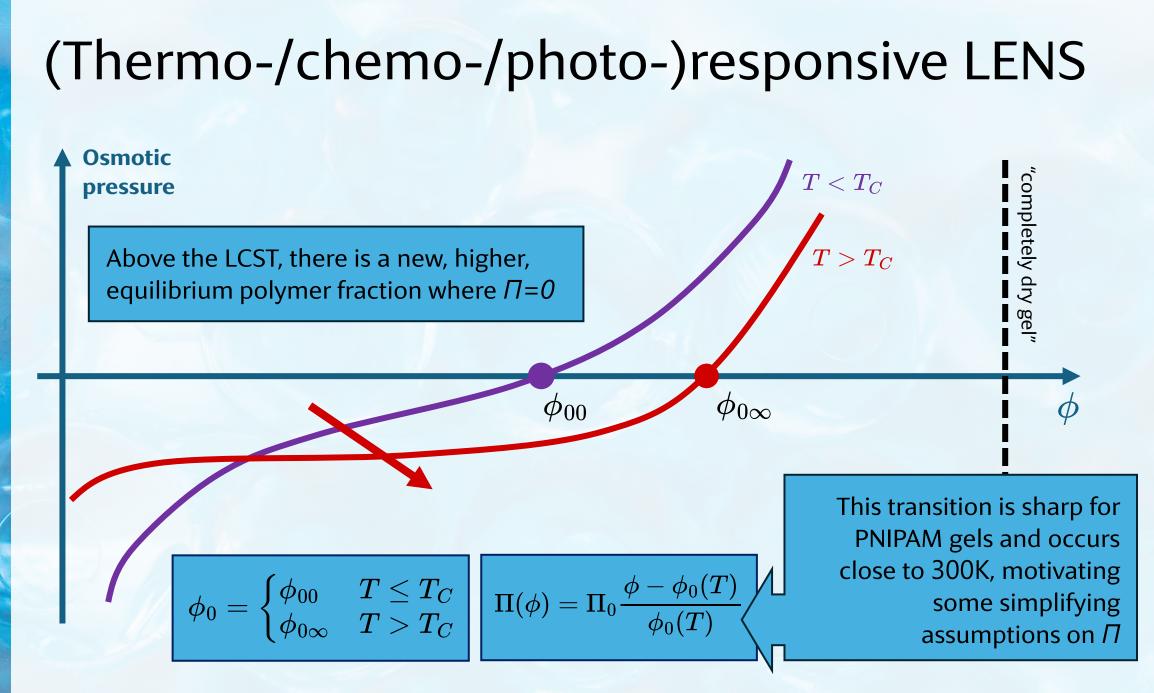
(Thermo-/chemo-/photo-)responsive LENS

(a) ANB parameters

(b) HHT parameters







Smart gels as machines

Sensors

- Can convert changes in the local environment to changes in shape
- Changes are large and predictable

e.g. a gel membrane becomes impermeable when a chemical concentration is high enough.

Actuators

- Programmable shape change is possible *via* swelling or deswelling
- Thermoresponsive gels
 can be impregnated with
 gold nanoparticles, and
 lasers lead to heating
 and deswelling

e.g. soft robotic grippers or valves that can be opened or closed

Smart gels as machines

Sensors

- Can convert changes in the local environment to changes in shape
- Changes are **large** and **predictable**

e.g. a gel membrane becomes impermeable when a chemical concentration is high enough.

Computers

Take input from sensors and use it to control actuators. Logic circuits make decisions and can provide feedback mechanisms.

e.g. artificial pancreas, smart pumps, hygrostat logic circuits,...

Actuators

- Programmable shape change is possible *via* swelling or deswelling
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 and deswelling

e.g. soft robotic grippers or valves that can be opened or closed

...all in one gel component?

Missing pieces: two gaps

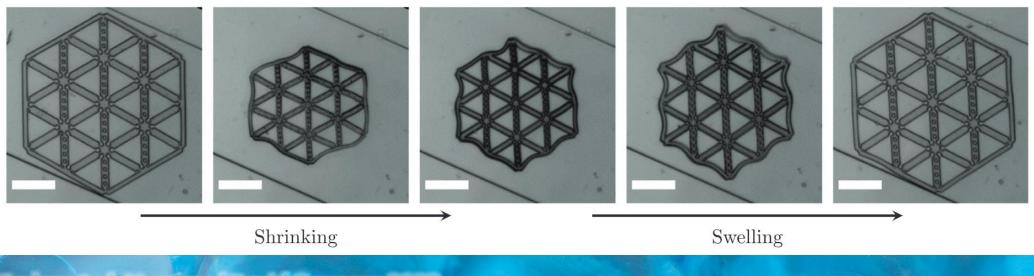
 Gels are already being used as actuators, and microfluidic devices employ thermo- and chemoresponsive mechanisms

$$\frac{\partial \phi}{\partial t} + \boldsymbol{q} \cdot \boldsymbol{\nabla} \phi = \boldsymbol{\nabla} \cdot \left\{ \frac{k(\phi)}{\mu_l} \left[\phi \frac{\partial \Pi}{\partial \phi} + \frac{4\mu_s(\phi)}{3} \left(\frac{\phi}{\phi_0} \right)^{1/3} \right] \boldsymbol{\nabla} \phi \right\} \xrightarrow{\sim 10^{-3} \text{ kg m}^{-1} \text{ s}^{-1}}_{\sim 10^4 \text{ kg m}^{-1} \text{ s}^{-2}} \xrightarrow{\mu_l L^2}_{\sim 10^{-15} \text{ m}^2}$$

- For second-scale responses, need $L \sim 10^{-4}$ m, which constrains us to microfluidics.
- We also have no way to communicate information between gel devices: computers require networking or connections between sensor and actuator to function.
- Both of these problems can be unlocked using the modelling we've already introduced

Problem 1: responsive gels are slow

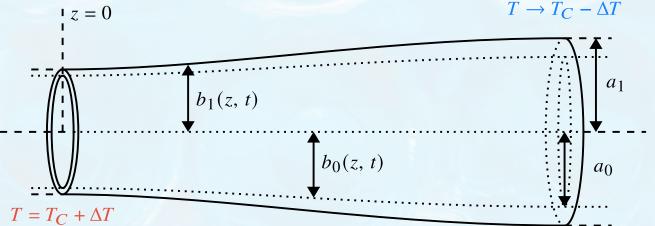
Building displacement pumps from hydrogel tubes



Maslen et al. Macromol Rapid Commun 2022

Porous media as a network of tubes

- Swelling and deswelling is more rapid when micropores are drilled into the gel structure, since the movement of water is no longer constrained by slow diffusion through the nanopores
- This technique has been used to make faster actuators (<u>Spratte *et al. Adv Intell Syst* 2022</u>, <u>Maslen</u> <u>*et al. Macromol Rapid Commun* 2022</u>)
- Can't just use a scaling argument to find how drilling micropores will affect response times; need to model the whole system! This hard traditionally, with a complex geometry, and perhaps easier with LENS

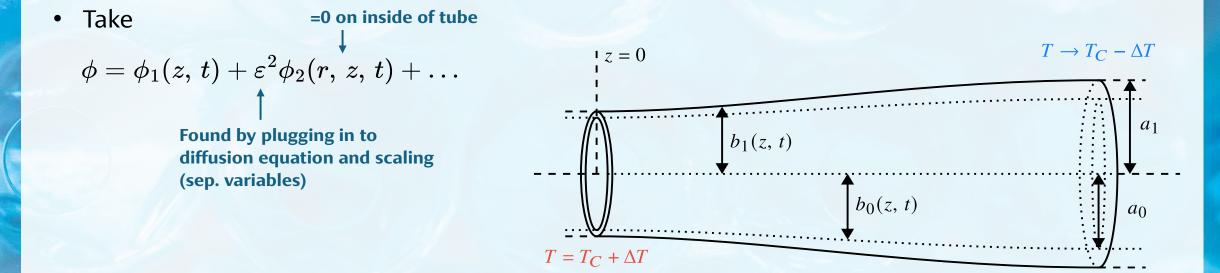


Displacement modelling

- To make modelling easier, take a slenderness assumption $\varepsilon = a_1 / L \ll 1$
- Assume that the deswelling is locally isotropic, and therefore

$$rac{b_1}{a_1} = rac{b_0}{a_0} = \left(rac{\phi}{\phi_{00}}
ight)^{-1/3}$$

where ϕ is the polymer fraction on the inside of the tube, at leading order.



Polymer fraction evolution

• Separation of variables implies that we must just solve for ϕ_1 , with the radial structure function deduced from boundary conditions on the outside of the tube:

$$\frac{\partial \phi_1}{\partial t} + q_z \frac{\partial \phi_1}{\partial z} = f(z, t, T) + \frac{\partial}{\partial z} \begin{bmatrix} D(\phi_1, T) \frac{\partial \phi_1}{\partial z} \end{bmatrix} \qquad \phi_2 = \frac{f(z, t, T)}{4D(\phi_1, T)} \begin{bmatrix} r^2 - \frac{\ell^2(\phi_1/\phi_{00})^{-2/3}}{\log \ell + \log \left[(\phi_1/\phi_{00})^{-1/3}\right]} \end{bmatrix}$$

$$\begin{array}{c} \text{Total (phase-averaged) flux} \quad \text{Separation} \\ \text{averaged) flux} \quad \text{"constant"} \end{array} \qquad \text{Nonlinear diffusivity} \qquad \phi_2 = \frac{f(z, t, T)}{4D(\phi_1, T)} \begin{bmatrix} r^2 - \frac{\ell^2(\phi_1/\phi_{00})^{-2/3}}{\log \ell + \log \left[(\phi_1/\phi_{00})^{-1/3}\right]} \end{bmatrix}$$

- Boundary conditions arise from:
 - Decay in perturbations from equilibrium as $z \to \infty (\partial \phi / \partial z \to 0)$
 - Symmetry around z=0 ($\partial \phi / \partial z = 0$)
 - No stress on outer boundary ($\phi = \phi_0(T)$ on $r = b_1$) which gives

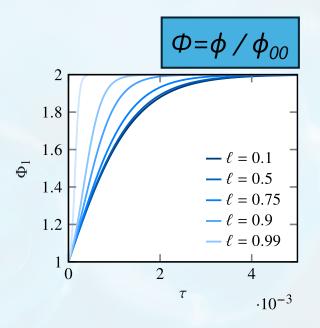
$$f(z,\,t,\,T) = rac{4D(\phi_1,\,T)}{arepsilon^2} igg(rac{\phi_1}{\phi_{00}}igg)^{2/3} rac{3\log\ell - \log{(\phi_1/\phi_{00})}}{3\log\ell - (1-\ell^2)\log{(\phi_1/\phi_{00})}} [\phi_0(T) - \phi_1]^2$$

joe.webber@warwick.ac.uk

Heat transfer

- We have a model for the response of a tube to a time- and spacevarying temperature field *T*(*z*, *t*)
- If we instantaneously raise the temperature above the LCST, water is expelled into the lumen and into the surroundings and the tube collapses uniformly (flows are a second-order effect that don't change the dynamics in a thin tube)
- Introduce the Lewis number *Le* which is the ratio of heat diffusivity to compositional diffusivity. For these tubes, *Le* ~ 10-100 and so we make the large-*Le* approximation that a heat pulse is purely diffusive

$$rac{\partial T}{\partial z} = \kappa rac{\partial^2 T}{\partial z^2} \qquad egin{cases} T(z,\,0) = T_C - \Delta T \ T(0,\,t) = T_C + \Delta T \ \partial T/\partial z o 0 ext{ as } z o \infty \end{cases}$$



$$T-T_C = \Delta T \left[2 \operatorname{erfc} \left(rac{z}{2 \sqrt{\kappa t}}
ight) - 1
ight]$$

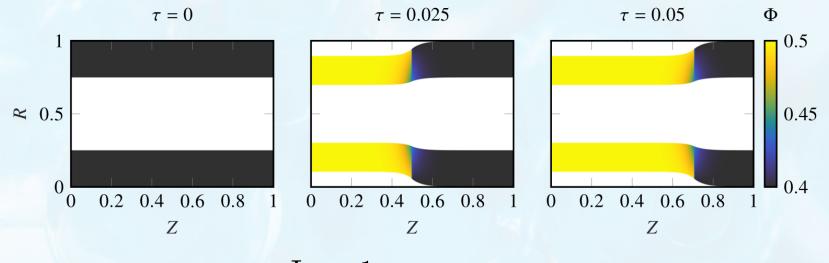
Step/tanh approximation

- Non-dimensionalise: times on the poroelastic timescale, axial lengths on the lengthscale L, radial lengths on a₁
- The heat front (behind which the temperature is above the LCST) is given by

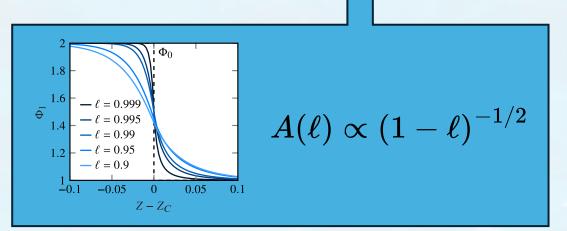
 $Z_C(au) = 2\,{
m erfc}^{-1}\,igg(rac{1}{2}igg)\sqrt{Le\, au}$ $\tau = 0$ $\tau = 0.05$ $\tau = 0.025$ Φ 0.5 ≈ 0.5 0.45 0 0.4 0 0.2 0.4 0.6 0.8 1 0.2 0.4 0.6 0.8 0 0.2 0.4 0.6 0.8 1 0 Ζ Ζ Ζ

$$\Phi_1pprox \Phi_\infty - rac{\Phi_\infty - 1}{2} \{1 + anh\left[A(\ell)\left(Z - Z_C
ight)
ight]\}$$

Step/tanh approximation



$$\Phi_1pprox \Phi_\infty - rac{\Phi_\infty - 1}{2} \{1 + anh\left[A(\ell)\left(Z - Z_C
ight)
ight]\}$$



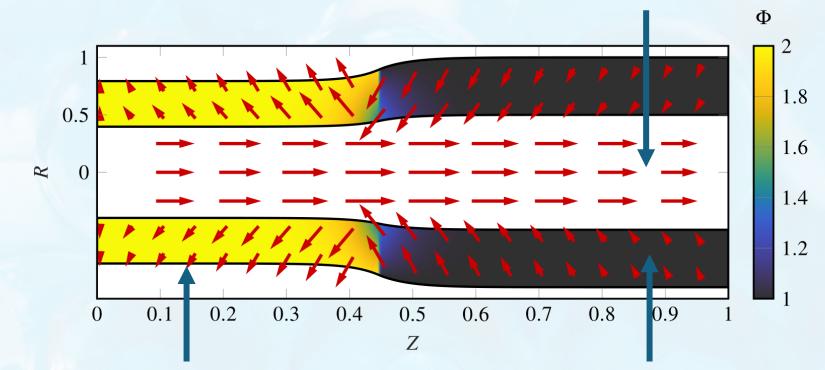
joe.webber@warwick.ac.uk

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Flows in the gel

Flows through the lumen

Poiseuille flow driven through the middle; fastest, given by "squeezing" fluid out of place



Flows out of the gel and into the surrounds

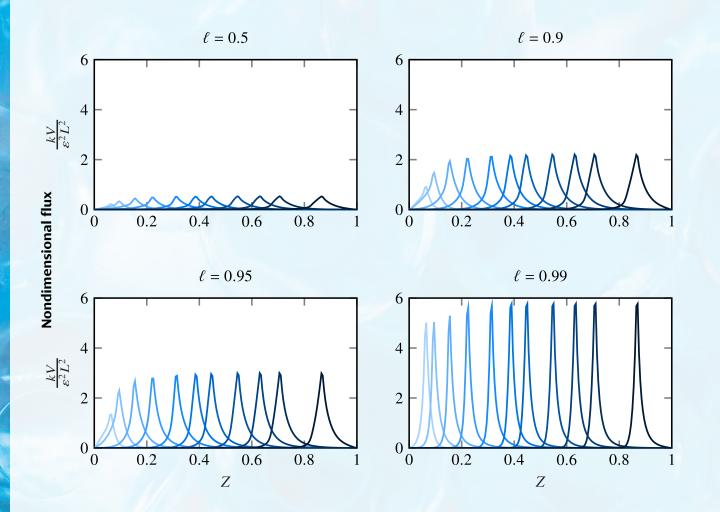
The principal route for water loss – the outside instantaneously dries and interstitial flows are sent towards the drier gel regions

Flows through the gel

Very slow, with limited net flux since the tube is thin <u>and</u> transport is mediated by the low permeability

 $egin{aligned} p+\Pi(\phi_1) &= 0 \ \Rightarrow p &= \Pi_0(1-\phi/\phi_0(T)) \end{aligned}$

Fast(ish) flows in the lumen



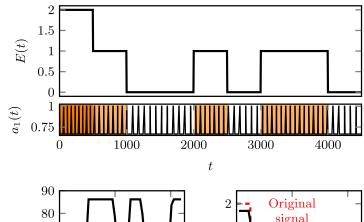
- Thinner tubes have a faster response and so lead to larger peak velocities at the deswelling front
- However, the sharpness of the profile is greater when l → 1 so the total integrated transport is approximately constant in l
- Have an expression for fluxes and response times:
 - Chain together to make porous media
 - Scaling law from many joined tubes

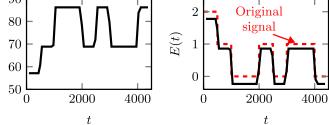
Problem 2: responsive gels don't talk

Oscillating reactions lead to communication









The BZ reaction

- There are very few chemical reactions that naturally oscillate with a predictable period, and even fewer that are (relatively) straightforward to model mathematically
- The BZ (Belousov-Zhabotinsky) reaction was discovered in the mid-20th century and is often modelled using reduced systems of autocatalytic reactions
- In this proof-of-concept, we will use the Brusselator model where

 $A \rightarrow X$ $2X + 3Y \rightarrow 3X$ $B + X \rightarrow Y + D$ $X \rightarrow E$

- Clearly D and E have no effect on the dynamics
- Assume A, B are in excess so their concentrations are constant

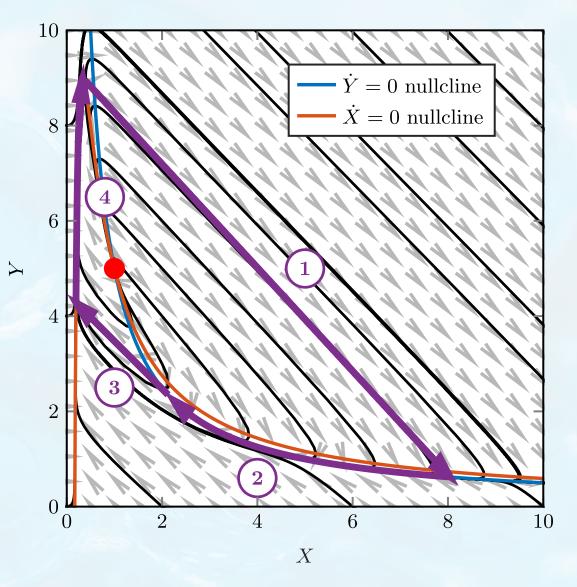
The BZ reaction

$$egin{aligned} rac{\mathrm{d}X}{\mathrm{d}t} &= A + X^2Y - (1+B)X \ rac{\mathrm{d}Y}{\mathrm{d}t} &= BX - X^2Y \end{aligned}$$

 $(X^*,\,Y^*)=(A,\,B/A)$

• The time spent on the limit cycle can be approximated: dynamics are fast in regions 1-3 until we collapse onto the *X* nullcline

$$Tpprox \int_{0}^{Y_{
m max}} rac{dY}{\dot{Y}}pprox rac{(1+B)^2}{4A^2}$$



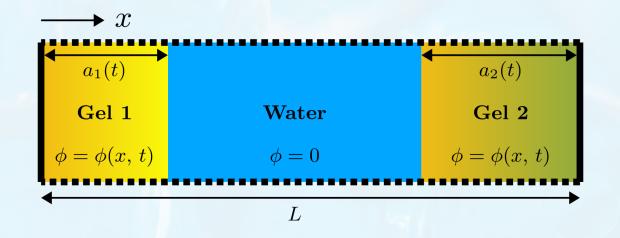
Coupling with gel dynamics

- Oscillating chemical reactions have been coupled with chemo-responsive gels to create periodic shape changes in the modelling of heart tissues (<u>Yoshida, *Biophysics Nagoya-Shi* 2012</u>), the creation of crawling microbots (<u>Mao et al. Extreme Mech Lett</u> 2020) and the development of soft machines (<u>Nava-Medina et al. Adv Mater Technol</u> 2021)
- In general, a catalyst molecule is chemically-bonded to the gel scaffold so that reaction rates increase in a dry gel and decrease in a swollen one
- The polymer will lose its affinity for water when the concentration of *Y* exceeds a set threshold

$$\phi_0(Y) = egin{cases} \phi_{00} & Y \leq Y_C \ \phi_{0\infty} & Y > Y_C \end{cases}$$

joe.webber@warwick.ac.uk

A model system



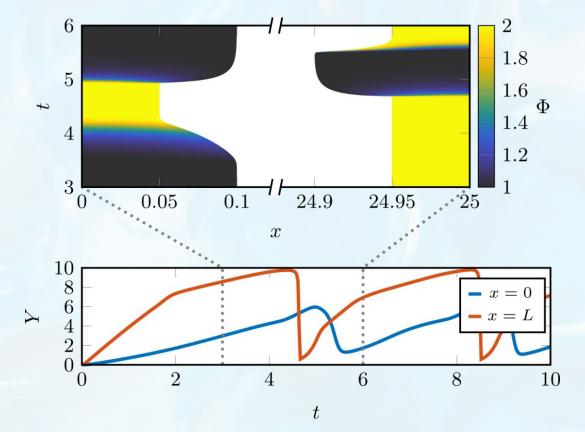
Swelling-dependent catalysis

$$\frac{\partial X}{\partial t} + q \frac{\partial X}{\partial x} = r(\phi) \left[A + X^2 Y - (1+B)X \right] + \mathcal{D} \frac{\partial^2 X}{\partial x^2}$$
$$\frac{\partial Y}{\partial t} + q \frac{\partial Y}{\partial x} = r(\phi) \left[BX - X^2 Y \right] + \mathcal{D} \frac{\partial^2 Y}{\partial x^2}$$

Pumping of interstitial fluid in gel Equal to zero outside of gel, given by fluid fluxes within the gel (water flow from swollen to dried regions)

Chemical diffusion Faster in water than impermeable gel Couple this with familiar gel dynamics

A model system



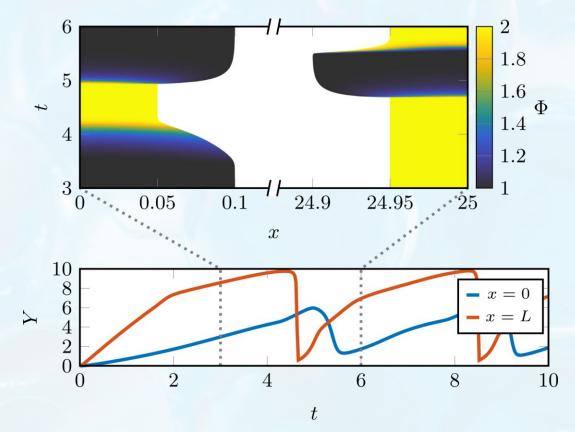
Parameters: A=1, B=5, L=25, $a_0 = 0.1$, reaction rate 5 times faster in right-hand gel, scaled diffusivities are 1000 in water, 0.2 in gel. $Y_C = 5$ and the equilibrium polymer fraction doubles above the critical threshold. The Damköhler number is 1.

- This system can be modelled numerically, taking into account:
 - Transport of water and solute into and out of gels as they deswell and swell
 - Molecular diffusion of chemical species
 - The BZ reaction in each gel
 - Changes to reaction rates due to swelling and deswelling
- Lots of timescales here, introduce

Rate constant
for reaction $Da_I = \frac{k_r \mu_l a_0^2}{k \Pi_0} \lesssim 1$ Gel permeability

i.e. assume reconfiguration is fast!

Coupled oscillator model



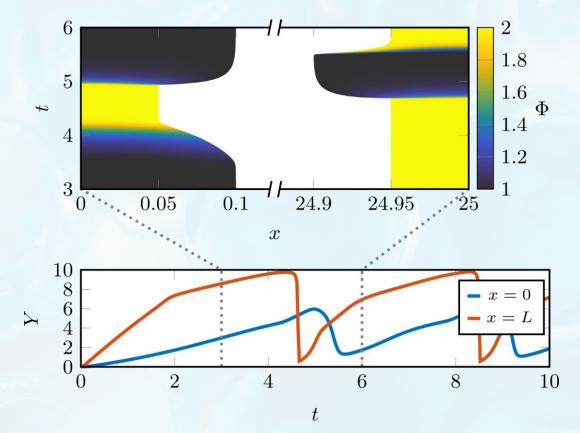
Parameters: A=1, B=5, L=25, $a_0 = 0.1$, reaction rate 5 times faster in right-hand gel, scaled diffusivities are 1000 in water, 0.2 in gel. $Y_C = 5$ and the equilibrium polymer fraction doubles above the critical threshold. The Damköhler number is 1. We can reduce these PDEs to a simpler coupled oscillator model, assuming:

- **Diffusion is fast** in gels, so chemical concentration is approximately constant within
- Diffusion is fast in water, so there are linear profiles here

$$X = X_1 + rac{X_2 - X_1}{L - a_1 - a_2}(x - a_1)
onumber \ Y = Y_1 + rac{Y_2 - Y_1}{L - a_1 - a_2}(x - a_1)$$

- Neglect osmotic pumping
- **Diffusion is much faster in water than in gel** so the diffusive flux in the water approximates the flow of chemical into or out of a gel.

Coupled oscillator model



Parameters: A=1, B=5, L=25, $a_0 = 0.1$, reaction rate 5 times faster in right-hand gel, scaled diffusivities are 1000 in water, 0.2 in gel. $Y_C = 5$ and the equilibrium polymer fraction doubles above the critical threshold. The Damköhler number is 1.

- **Diffusion is fast** in gel and water
- Neglect osmotic pumping
- Diffusion is much faster in water than in gel
- **Damköhler number is small** so gels instantaneously reach equilibrium

$$\frac{\mathrm{d}X_{1}}{\mathrm{d}t} = r(\phi_{0}(Y_{1}))R_{X}(X_{1}, Y_{1}) + \frac{Qa_{0}}{a_{1}}(X_{2} - X_{1}),$$

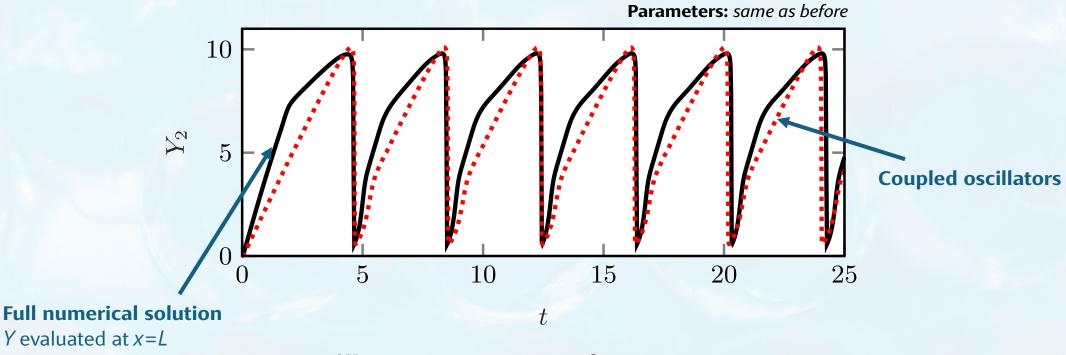
$$\frac{\mathrm{d}X_{2}}{\mathrm{d}t} = r(\phi_{0}(Y_{2}))R_{X}(X_{2}, Y_{2}) - \frac{Qa_{0}}{a_{2}}(X_{2} - X_{1}),$$

$$\frac{\mathrm{d}Y_{1}}{\mathrm{d}t} = r(\phi_{0}(Y_{1}))R_{Y}(X_{1}, Y_{1}) + \frac{Qa_{0}}{a_{1}}(Y_{2} - Y_{1}),$$

$$\frac{\mathrm{d}X_{2}}{\mathrm{d}t} = r(\phi_{0}(Y_{2}))R_{Y}(X_{2}, Y_{2}) - \frac{Qa_{0}}{a_{2}}(Y_{2} - Y_{1}).$$
Coupling strength Reaction terms
$$Q = D_{water} / a_{0}L$$

where e.g.
$$a_1/a_0 = \phi_{00}/\phi_0(Y_1)$$

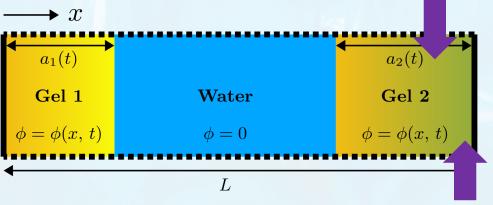
Coupled oscillator model



$$egin{aligned} rac{\mathrm{d}X_1}{\mathrm{d}t} &= r(\phi_0(Y_1))R_X(X_1,\,Y_1) + rac{Qa_0}{a_1}(X_2-X_1), \ rac{\mathrm{d}X_2}{\mathrm{d}t} &= r(\phi_0(Y_2))R_X(X_2,\,Y_2) - rac{Qa_0}{a_2}(X_2-X_1), \ rac{\mathrm{d}Y_1}{\mathrm{d}t} &= r(\phi_0(Y_1))R_Y(X_1,\,Y_1) + rac{Qa_0}{a_1}(Y_2-Y_1), \ rac{\mathrm{d}X_2}{\mathrm{d}t} &= r(\phi_0(Y_2))R_Y(X_2,\,Y_2) - rac{Qa_0}{a_2}(Y_2-Y_1). \end{aligned}$$

Gels squeal under pressure

- In the first example, we arbitrarily set the reaction rate faster in the second gel than in the first this gave limit cycles of different periods on each side
- The polymer fraction varies under changes in chemical concentration, but it can also be varied by applying a strain to one gel

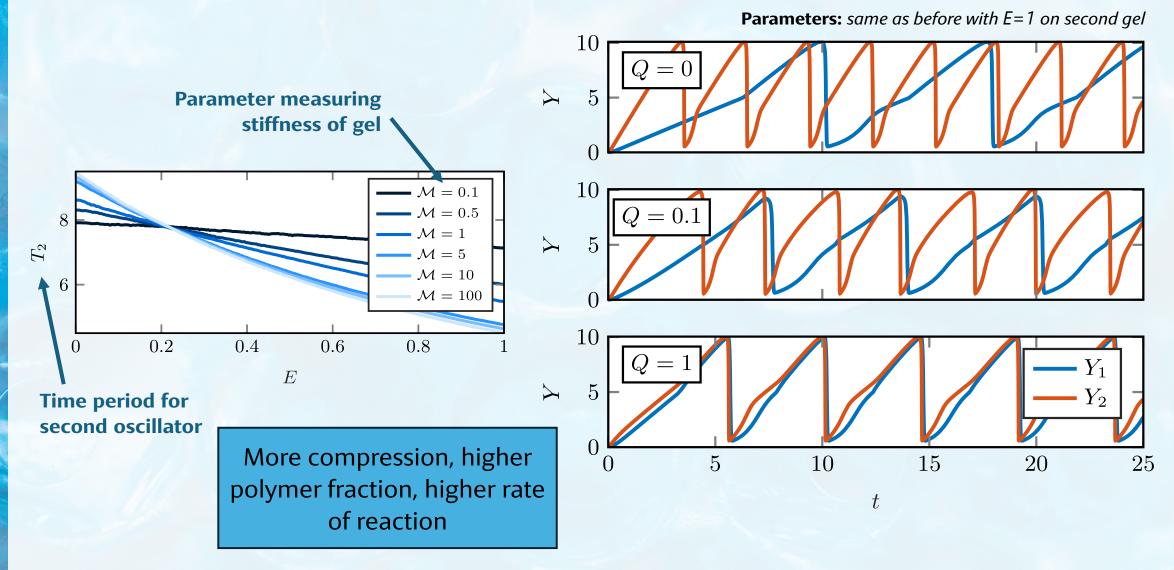


Applying a fixed strain *E*(*t*) This allows us another control on the polymer fraction and therefore on the reaction rate here

For a stiff gel, $\Phi \approx (1+E)^2$

 For stronger coupling (Q large), there is a penalty to a nonzero value of X₂-X₁ or Y₂-Y₁ – therefore, if the two gels are especially close or the diffusion of chemical species is fast through the gap, there is synchronisation in their periods

Gels squeal under pressure



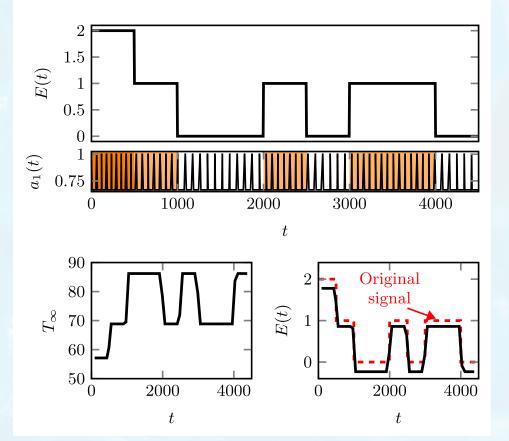
Where does this leave us?

 We can modulate the compression on the second gel and measure the time period of the oscillations of the first gel. In the limit of strong coupling

$$T_1 pprox T_2 pprox rac{(B+1)^2}{2(r_1+r_2)A^2}$$

 Seeing as the reaction rate of the first gel is known, this allows us to measure the reaction rate of the second gel and therefore find the compression that is being applied, allowing for communication





Next steps

Sensors

- Can convert changes in the local environment to changes in shape
- Changes are large and predictable

e.g. a gel membrane becomes impermeable when a chemical concentration is high enough.

Computers

- Gels can communicate
 with one another to
 coordinate actuators and
 sensors
- Could string together switches to build logic gates

Actuators

- Actuators can be created with tuneable response times
- Bilayers/materials with
 varying porosity allow for
 non-reciprocal shape
 changes and the design
 of complex devices
- Automatic smart pumps
- Can devise a general model for microporous hydrogels

...all in one gel component?

joe.webber@warwick.ac.uk

Next steps

Even though hydrogels have been modelled for decades, there's still a need for **simple**, **macroscopic** models that capture the key phenomena without recourse to microscopic modelling: these can both follow experimental advances (tubes) or inform new implementations (communicating gels)

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Modelling hydrogels: building networks in the Mathematical Sciences

Mathematical Interdisciplinary Research at Warwick (MIR@W) Day Warwick Mathematics Institute, 9th December 2024

Organisers: Joe Webber and Tom Montenegro-Johnson

1. Living gels, living with gels: hydrogels in microbiology and medicine

2. At the surface and through the pores: transport and interfacial behaviour

3. Feeling the surroundings: hydrogels as smart materials

Confirmed speakers

- Matthew Butler (UCL)
- Matt Hennessy (Bristol)
- Chris MacMinn (Oxford) (
- Philip Pearce (UCL)
- Draga Pihler-Puzović (Manchester)
 - Grae Worster (Cambridge)

