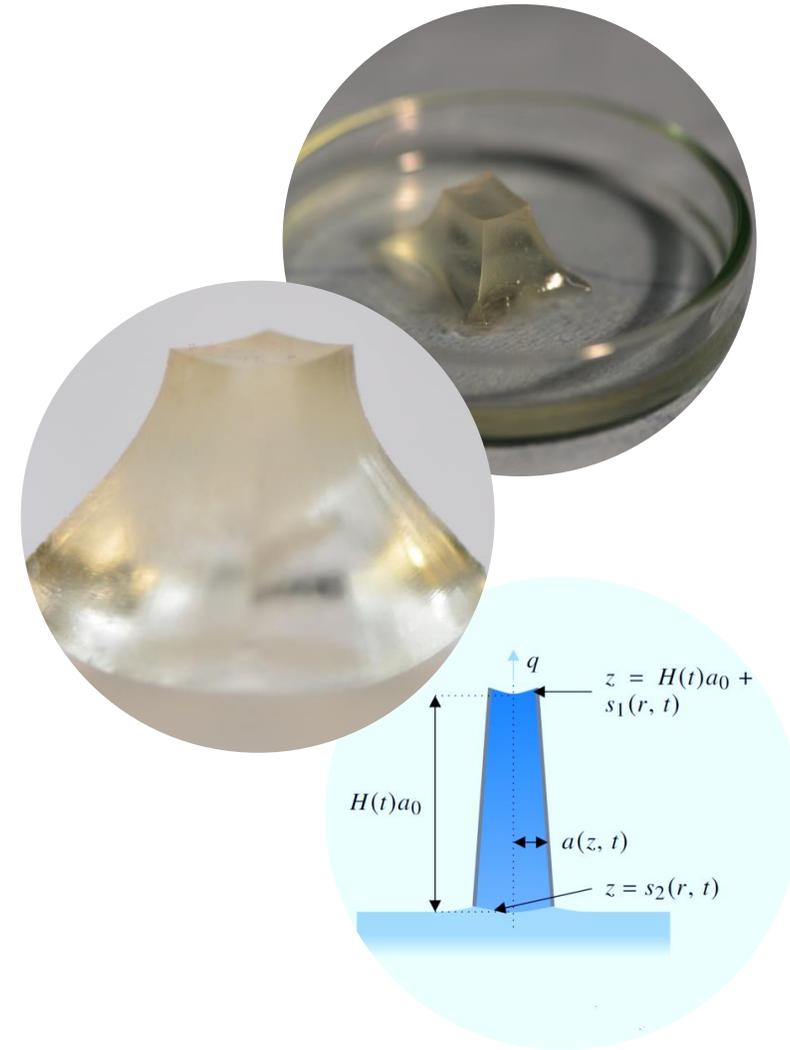


Multidirectional gel swelling and drying

A linear-elastic-nonlinear-swelling theory for hydrogels

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Modelling super-absorbent polymers

- Super-absorbent polymers (SAPs) are characterised by polymer fractions often as small as 1% by volume at equilibrium.
- Therefore, large (>100%) swelling strains are involved in the transition from partially-dry to fully-swollen states.

LINEAR POROELASTICITY

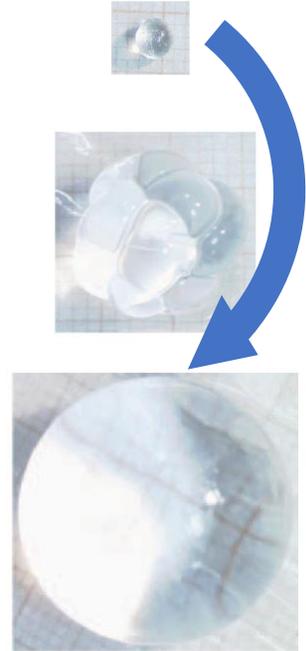
[Biot \(1941\)](#), [Doi \(2009\)](#), [Punter *et al.* \(2020\)](#)

- Analytically-tractable; treats the gel as a linear-elastic material separating pore pressure from material elasticity.
- *But* linear elasticity is only valid for small strains – to describe large swelling this is inadequate.

NONLINEAR (FREE-ENERGY) APPROACH

[Flory & Rehner \(1943a,b\)](#), [Bertrand \(2016\)](#)

- Derive a free-energy density from a microscopic understanding of the material.
- *But* this requires an understanding of intermolecular interactions and doesn't separate out the phases.



Linear-elastic-nonlinear-swelling theory

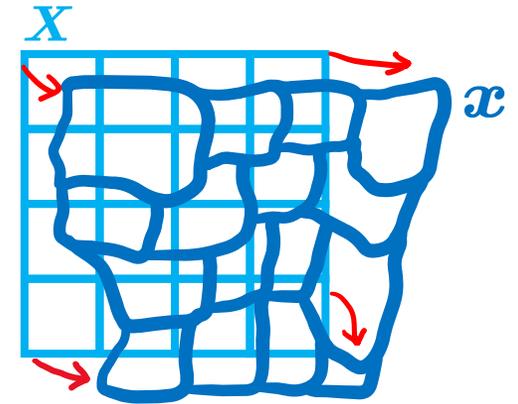
- Take the reference state for a gel to be the fully-swollen equilibrium, $\phi \equiv \phi_0$.
- Label gel elements in this state by Lagrangian coordinates \mathbf{X} and introduce the displacement $\boldsymbol{\xi}(\mathbf{x}) = \mathbf{x} - \mathbf{X}$ to represent a deformation.

$$\mathbf{e} \equiv \frac{1}{2} \left[\nabla \boldsymbol{\xi} + (\nabla \boldsymbol{\xi})^T \right]$$
$$\equiv \left[\mathbf{1} - \left(\frac{\phi}{\phi_0} \right)^{1/n} \right] \mathbf{I} + \boldsymbol{\epsilon}$$

Volume changes correspond to changes in polymer fraction since

$$\det [\partial x_i / \partial X_j] = \phi_0 / \phi$$

The key idea underpinning our model is that deviatoric strains are small and thus we have linear elasticity in all but swelling strain.



The constitutive relation and pressure

- Treating the gel, when swollen to a certain degree, as a linear elastic material, the stress tensor is given by

$$\boldsymbol{\sigma} = -P\mathbf{I} + 2\mu_s\boldsymbol{\epsilon}$$

where P is the bulk pressure and μ_s is the shear modulus.

- Allow for nonlinearities in polymer fraction, and therefore $\mu_s = \mu_s(\phi)$.
- Separate $P = p + \Pi$ into **pervadic pressure** p (Peppin et al. 2005) and osmotic pressure Π , where the former is the pressure as measured by a transducer separated from the liquid by a partially-permeable membrane.

$$\boldsymbol{\sigma} = -(p + \Pi)\mathbf{I} + 2\mu_s(\phi)\boldsymbol{\epsilon}$$


$$= K(\phi)\frac{\phi - \phi_0}{\phi_0}$$

Gel dynamics

- Dynamics are governed by the flow of water through the gel structure, with interstitial flow described by Darcy's law, arising from gradients in pervadic pressure.
- We have three equations from which a governing equation for the change of polymer fraction in time can be derived:
 - Polymer conservation
 - Water conservation
 - Cauchy's momentum equation

$$\frac{\partial \phi}{\partial t} + \mathbf{q} \cdot \nabla \phi = \nabla \cdot \left[\frac{\phi k(\phi)}{\mu_l} \left\{ \nabla \Pi(\phi) + 2(n-1)\mu_s(\phi) \nabla \left(\frac{\phi}{\phi_0} \right)^{1/n} \right\} \right]$$

← Permeability

$$\mathbf{q} = \phi \mathbf{u}_p + (1 - \phi) \mathbf{u}_l$$

← advective term

We henceforth consider the low-Péclet number limit where diffusive behaviour dominates advection.

Boundary conditions and the shape of a gel

- In order to solve the equation we have derived, we need boundary conditions, usually at the interface between gel and air/water/other media:
 - Continuity of normal stress
 - Continuity of tangential stress
 - Fixed evaporative flux
 - Impermeable boundaries $\mathbf{n} \cdot \nabla p = 0$
- However, we don't actually know the position of the boundary – in one-dimensional swelling problems, we can use polymer conservation. Need a different approach for general problems.
- Can we find the displacement field given polymer fraction? Not immediately, all we know is $\nabla \cdot \boldsymbol{\xi} = n \left[1 - (\phi/\phi_0)^{1/n} \right]$.
- Recall in linear elasticity that $\nabla^4 \boldsymbol{\xi} = \mathbf{0}$ in the absence of any body force.

Boundary conditions and the shape of a gel

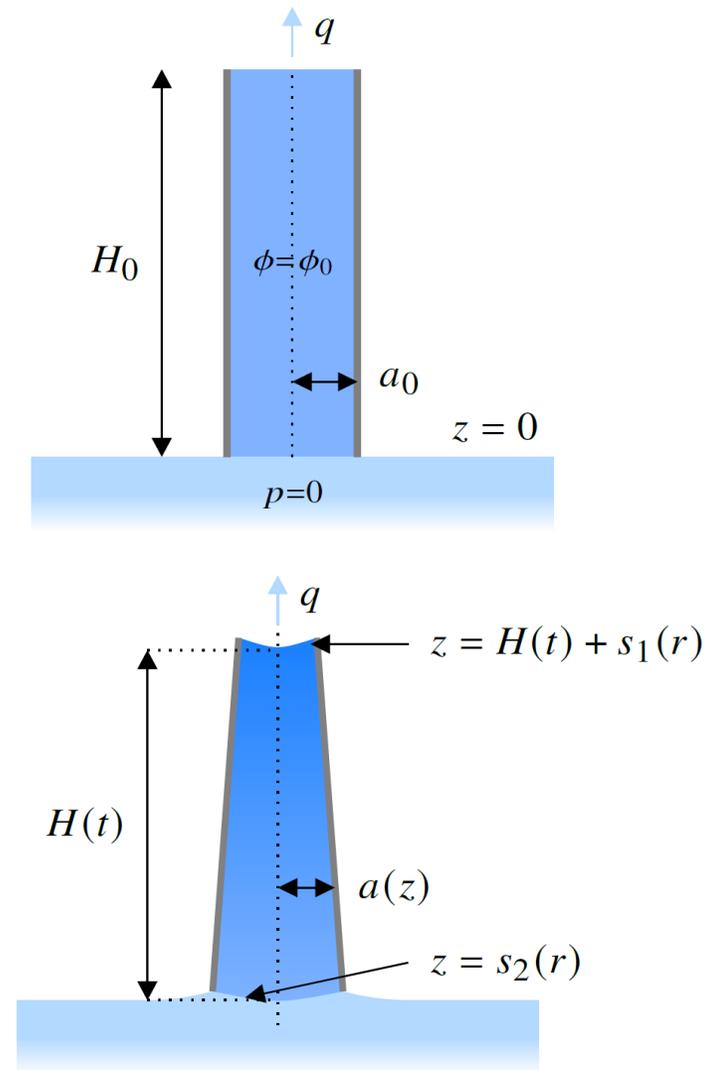
- In the case of the hydrogels we are considering, the assumption of small deviatoric strain alongside Cauchy's momentum equation in the absence of body forces implies that

$$\nabla^4 \xi = n \nabla \nabla^2 \left(\frac{\phi}{\phi_0} \right)^{1/n}$$

- Physically, this can be interpreted as a forcing due to curvatures in surfaces of constant polymer fraction.

Drying of slender cylinders

- Physical setup: cylinder of height H_0 and radius a_0 drying from its top surface only through a fixed evaporation flux q .
- Experiments show the formation of a curved interface on the top and bottom – can our model describe this?
- Start with the assumption that $H_0/a_0 \gg 1$ and solve for the polymer fraction and shape.
- Slenderness implies that $\phi(r, z) = \phi(z)$
- Can determine polymer fraction – seek the displacement field $\xi = \xi \hat{r} + \zeta \hat{z}$.



Drying of slender cylinders

$$\nabla^4 \zeta = \frac{\partial^3}{\partial z^3} \left(\frac{\phi}{\phi_0} \right)^{1/3} = O(\varepsilon^2) \quad \text{so} \quad \zeta = A(z)r^2 + B(z) + O(\varepsilon^2)$$

$$\xi = \frac{1}{2} \left\{ 3 \left[1 - \left(\frac{\phi}{\phi_0} \right)^{1/3} \right] - \frac{\partial B}{\partial z} \right\} r - \frac{1}{4} \frac{\partial A}{\partial z} r^3 \quad (\text{arising from } \nabla \cdot \xi = \text{tr } \mathbf{e})$$

Now require the deviatoric strain to be small, implying that

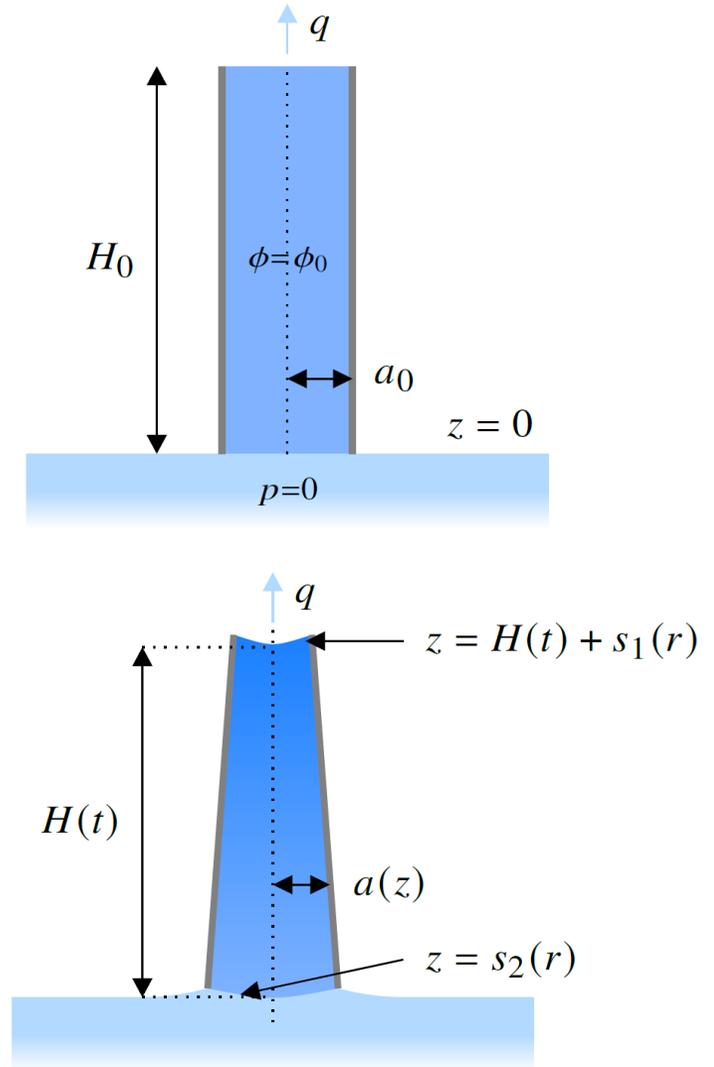
$$B(z) = \int_0^z 1 - (\phi/\phi_0)^{1/3} dz' + C(z) \quad \text{with } C(0) = 0 \text{ and } \partial C/\partial z = O(\varepsilon).$$

Zero tangential stress on the surface of the cylinder gives

$$A(z) = \frac{1}{2} \frac{\partial}{\partial z} \left(\frac{\phi}{\phi_0} \right)^{1/3}.$$

Calculate the bulk pressure field using Cauchy's momentum equation and impose zero normal stress on the surface to give

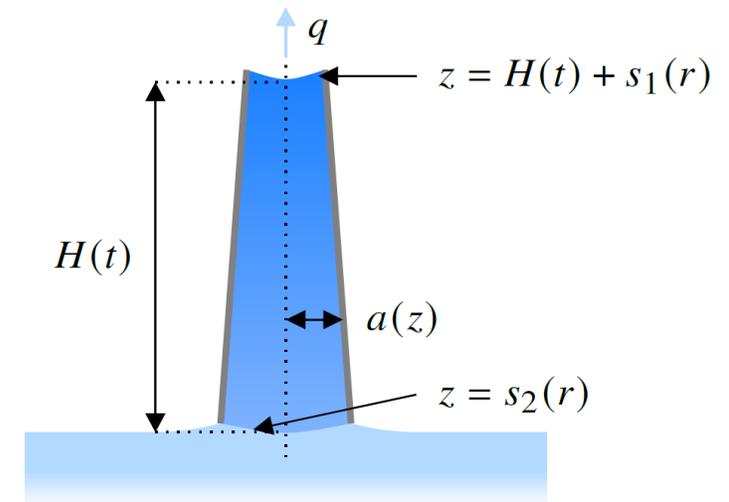
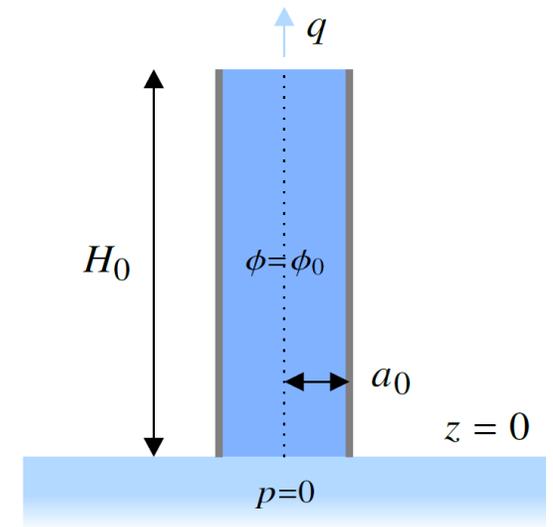
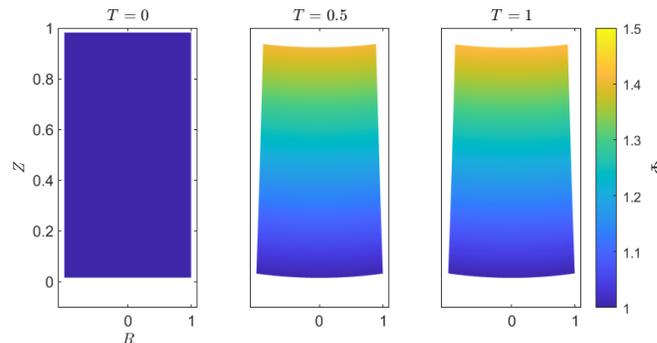
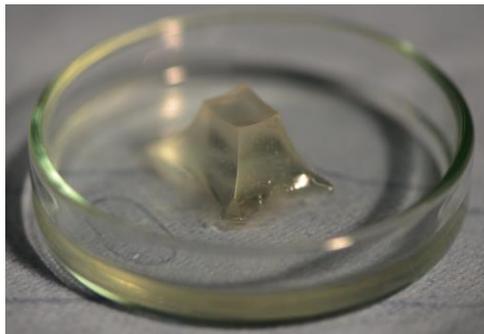
$$C(z) \equiv 0.$$



Drying of slender cylinders

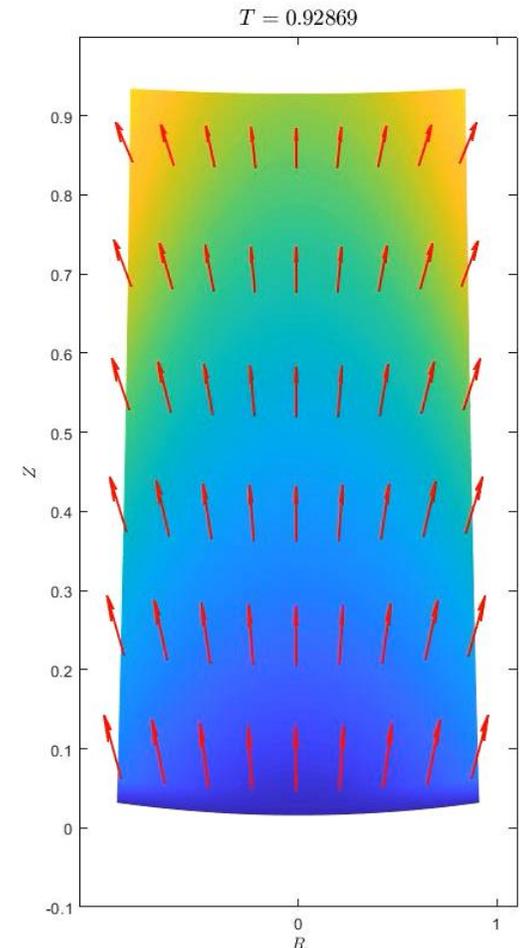
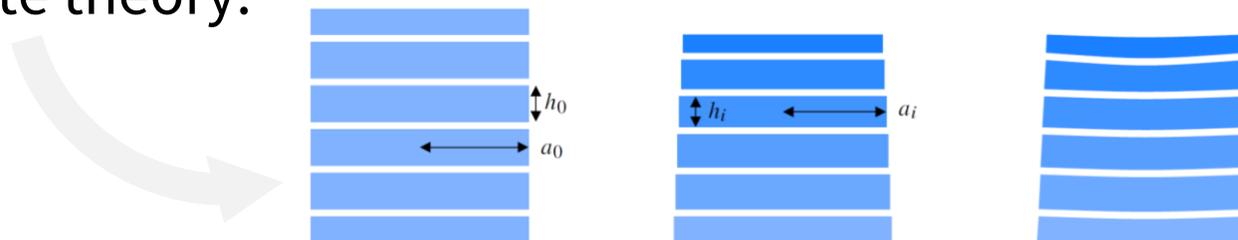
$$\left. \begin{aligned} \xi &= \left[1 - (\phi/\phi_0)^{1/3} \right] r, \\ \zeta &= \int_0^z 1 - (\phi/\phi_0)^{1/3} dz' + \frac{1}{2} \frac{\partial}{\partial z} \left(\frac{\phi}{\phi_0} \right)^{1/3} r^2. \end{aligned} \right\} \begin{cases} a(z) = (\phi/\phi_0)^{-1/3} a_0, \\ H_0 = \int_0^{H(t)} (\phi/\phi_0)^{1/3} dz'. \end{cases}$$

- Importantly, these results also show that the curvature of the top and bottom surfaces arises from gradients in polymer fraction.
- These results match those of experiments which show the formation of a convex base and concave top.



Drying of slender cylinders - comments

- The same approach can be applied when drying from the sides only (and not the top) in order to deduce the displacement field. Note in this case that $\phi = \phi(r, z)$ with $\phi = \phi_C(z) + \phi_1(z)r^2$.
- In any case, we approach a steady state when the evaporative flux balances the flux of water drawn up from the base, as illustrated here.
- These results agree with an alternative Lagrangian approach, where the cylinder is comprised of a stack of circular discs, drying isotropically and bending to accommodate differential swelling under classical plate theory.



Conclusions

- Current approaches to modelling super-absorbent hydrogels are either analytically-intractable, and hide the physical processes underlying the swelling and drying, or do not consider the large strains accurately.
- We have introduced a model which linearises around small deviatoric strains but allows for large isotropic strains to treat hydrogels as instantaneously linear-elastic whilst permitting a description of SAPs.
- This model can also describe the displacement field in more complicated multidirectional problems, unlike classical poroelastic approaches, and agrees qualitatively with experiments.



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Webber & Worster *A linear-elastic-nonlinear-swelling theory for hydrogels.*

Part 1. Modelling of super-absorbent gels

Webber, Etzold & Worster *A linear-elastic-nonlinear-swelling theory for hydrogels. Part 2. Displacement formulation*

J. Fluid Mech. (in prep)



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